#include<Servo.h>

Servo myservo;

int trigpin=7;

int echopin=5;

void setup()

{

pinMode(tarigpin,OUTPUT);

pinMode(echopin,INPUT);

Serial.begin(9000);

myservo.attach(4);

}

void loop()

{

digitalWrite(trigpin,HIGH);

delay(1000);

digitalWrite(trigpin,LOW);

int duration=pulseIn(echopin,HIGH);

int distance=(duration\*0.034)/2;

Serial.print("the distance of the car is");

Serial.println(distance);

if(distance<50)

{

myservo.write(0);

Serial.println("servo is at angle 0");

delay(1000);

myservo.write(90);

Serial.println("servo is at angle 90");

delay(1000);

myservo.write(180);

Serial.println("servo is at angle 180");

delay(1000);

myservo.write(0);

Serial.println("servo is at angle 0");

delay(1000);

}

else

{

digitalWrite(trigpin,LOW);

}

delay(1000);

}